

Euclid::Configuration  
::getMappingFileFromOptions



```
graph LR; A[Euclid::Configuration  
::getMappingFileFromOptions] --> B[std::map::at]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is gray with a black border and contains the text 'Euclid::Configuration' on the first line and '::getMappingFileFromOptions' on the second line. The right box is white with a black border and contains the text 'std::map::at'. A blue arrow points from the right side of the gray box to the left side of the white box.

std::map::at